

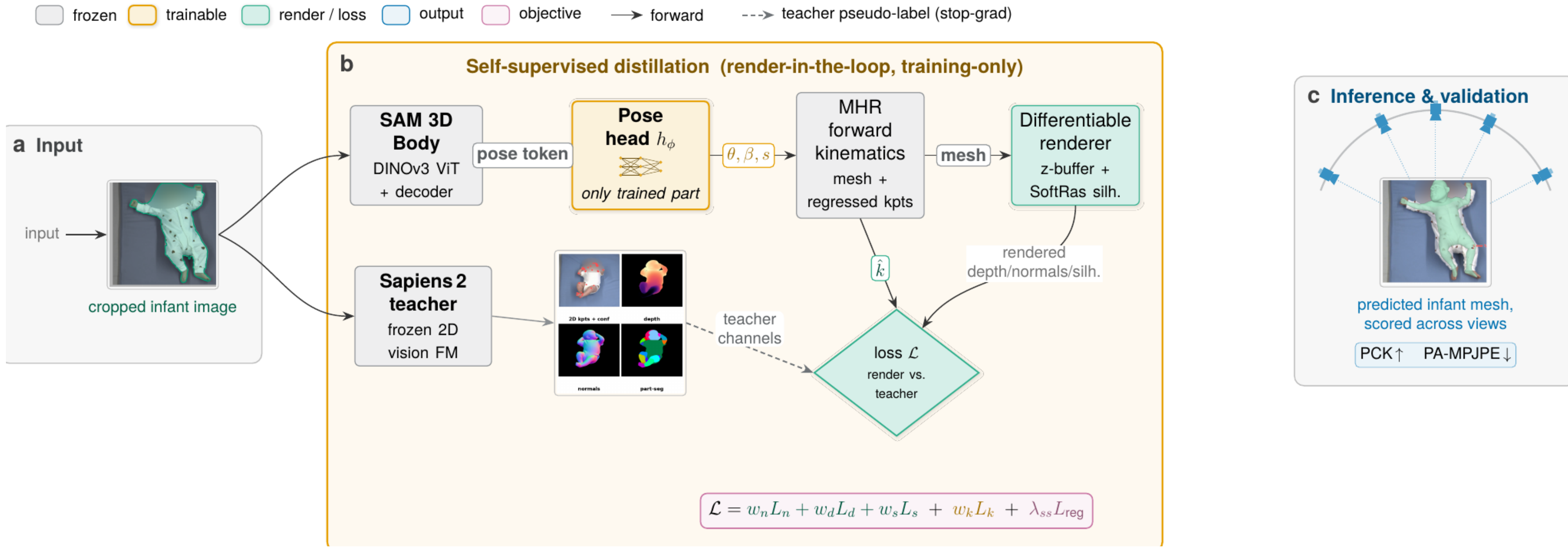
OVERVIEW

Problem Spontaneous movement is the earliest window onto an infant’s neuromotor health, but the instruments that score it need trained raters. Markerless capture is the scalable alternative — yet pose foundation models are trained on adults, infant labels are scarce, and affixing markers is impractical in infants.

Approach **Cross-model distillation from unannotated infant video alone:** a frozen Sapiens2 teacher supplies dense pseudo-labels (2D keypoints, depth, normals, segmentation) and a **differentiable renderer** aligns the SAM-3D-Body student’s mesh to them in the training loop. Only the pose head moves.

Result On 11 held-out infants (18 sessions, 173 recordings) keypoint agreement with the teacher **roughly doubles** (body PCK@10 0.22 → 0.42) and 3D PA-MPJPE improves **25.5 → 22.2 mm** — with **no labels and no markers**.

METHOD — RENDER-IN-THE-LOOP CROSS-MODEL DISTILLATION



Teacher — frozen Sapiens 2

- Dense pseudo-labels, emitted *live*: 2D keypoints + confidences, depth, normals, segmentation.
- Crop & mask: SAM3 prompted “**baby**” — selects the subject by concept, not size.

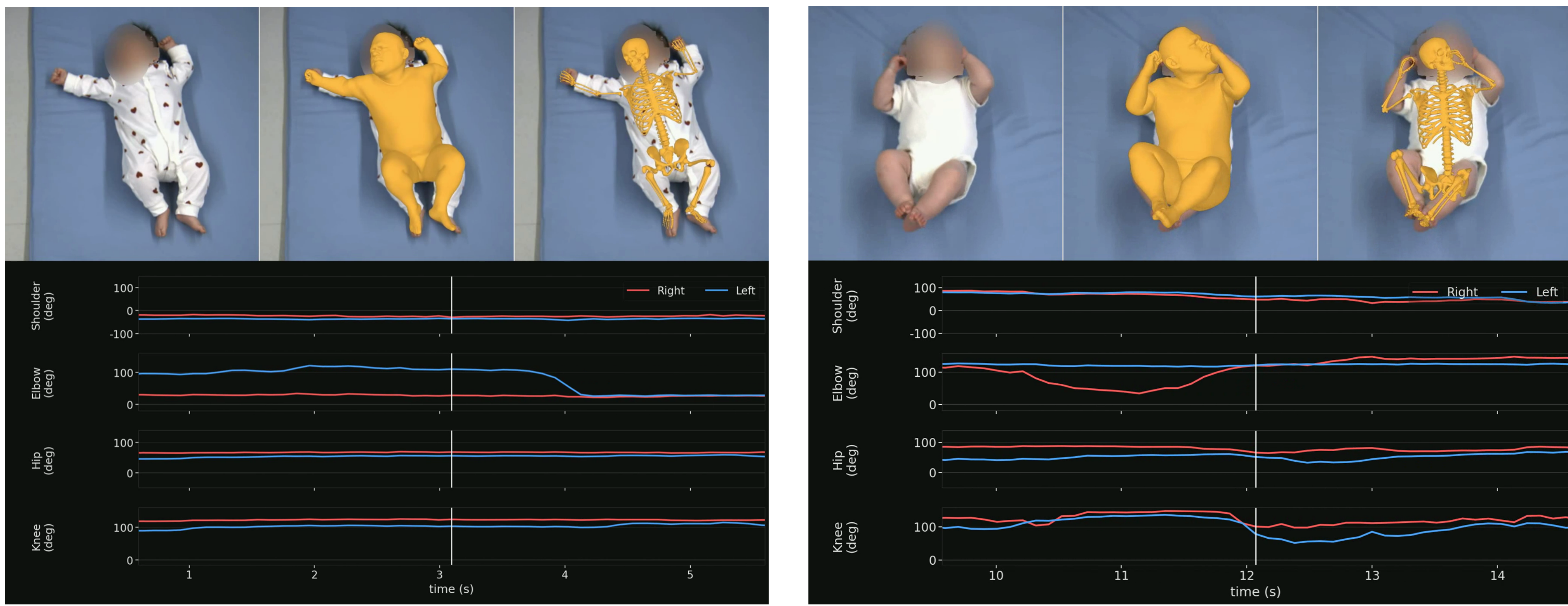
Student — SAM-3D-Body

- Only the **pose head** trains (backbone, decoder, FK frozen); gradient **masked on shape & scale rows** — unfreezing them inflates proportions.
- **Corpus**
 - 543 unannotated recordings, 311 infants; skews preterm (median gestational age 31 wk).
 - 11 validation infants excluded at index build — leakage-free split.

Objective

- $\mathcal{L} = w_{\text{kpt}} L_{\text{kpt}} + w_{\text{normal}} L_{\text{normal}} + w_{\text{depth}} L_{\text{depth}} + w_{\text{silh}} L_{\text{silh}}$
- Keypoints: confidence-weighted, *mask-gated* (caregiver limbs excluded, not fit) — **98%** of the converged objective.
- Depth affine-aligned; soft-rasterized silhouette gives outline gradient.

SINCE THIS PAPER — DISTILLING INFANT *biomechanics*



Two held-out infants: **tracked crop** | **MHR mesh** | **biomechanical skeleton** + joint angles.

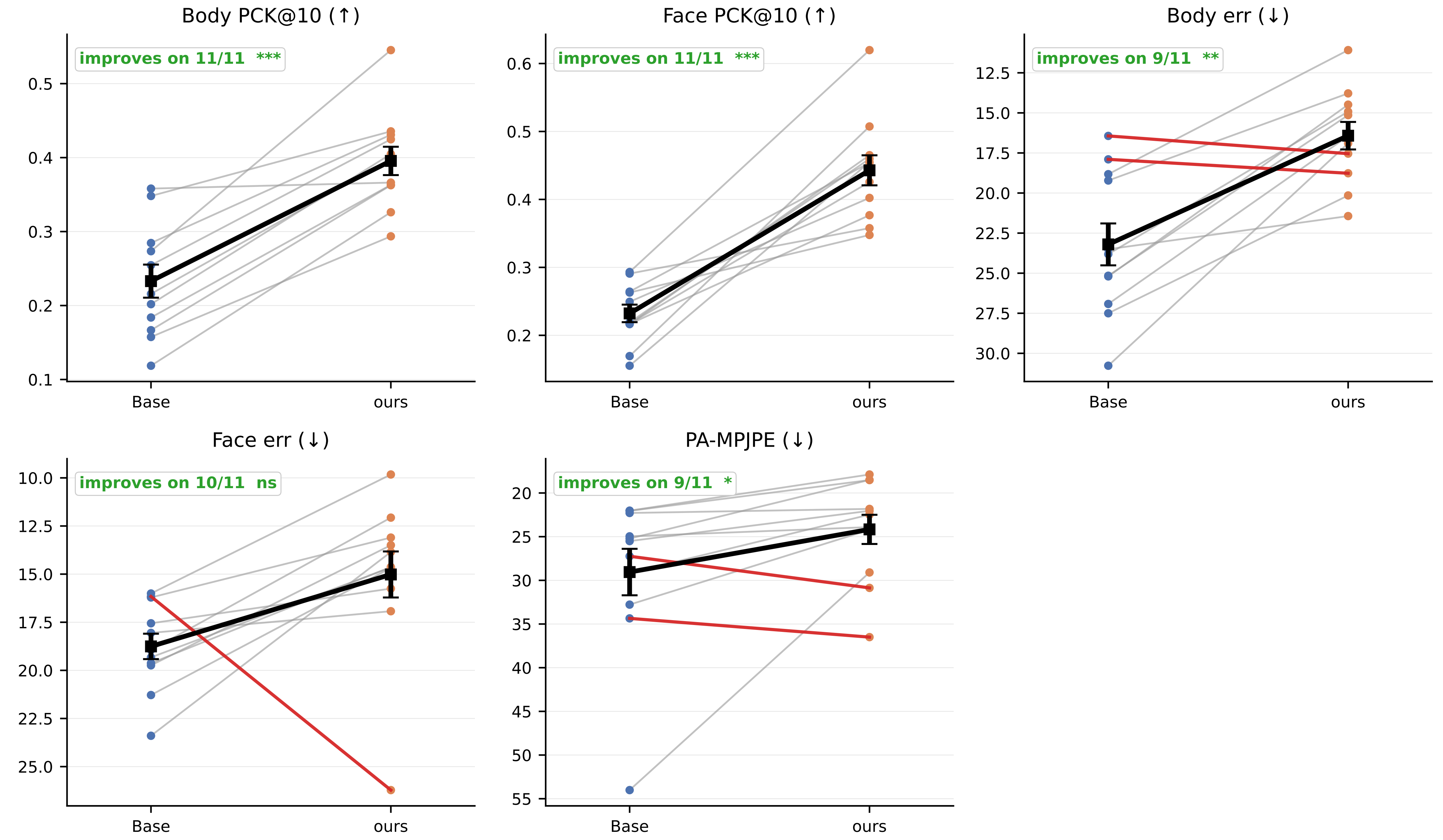
- A companion **biomechanical head** now trains *together* with the distillation above — emitting infant movement as **joint angles**.
 - Three epochs in, in-the-loop IK barely corrects it: median **hip 1.0–1.1°**, **knee 0.3–0.5°**, **elbow 0.6–0.7°** (from 5–15° and 5–11°); skeleton outside the mesh **6.9% → 1.3%**.
 - **Preliminary:** the raw head is still 4× its IK-refined output; one held-out monocular clip got slightly worse; **no infant biomechanical ground truth exists to score it against**.
- Method:** *Biomechanical 3D Body: Self-Supervised Distillation of Biomechanical Pose from a 3D Body Foundation Model*, Cotton et al., ECCV Workshop on Human Motion Challenges in Real-World and Clinical Settings (MoCha) 2026. arXiv:2608.29928.

TAKEAWAYS

- Adapting a 3D body model to a data-scarce population needs **no infant pose labels and no markers** — a frozen teacher, unlabeled video, and a differentiable render to connect them.
- Gains hold **across almost the whole cohort** and are significant on every headline metric (paired Wilcoxon, $p \leq 0.005$).

RESULTS — GAINS HOLD ACROSS ALMOST THE WHOLE COHORT

Per-infant change, base → fine-tuned (ours). Each line is one infant; y inverted where lower is better, so up = better in every panel.



Per-infant change on the 11 held-out infants, base → fine-tuned (*up is better*): **PCK improves on all 11** and every improvement is significant (paired Wilcoxon, $p \leq 0.005$).

QUANTITATIVE — 11 HELD-OUT INFANTS

Metric	Sapiens	SAM-3D-Body	Ours
<i>Multi-view consistency</i>			
Reprojection (px) ↓	22.8	39.8	36.7
GC@10 ↑	0.82	0.31	0.36
<i>Teacher agreement</i>			
Body PCK@10 ↑	—	0.216 (0.08)	0.418 (0.09)
Face PCK@10 ↑	—	0.219 (0.03)	0.422 (0.09)
PA-MPJPE, 11 core joints (mm) ↓	—	25.5 (5.4)	22.2 (3.6)
PA-MPJPE, + hips (13 kpt) (mm) ↓	—	33.4 (20.8)	25.1 (20.1)
PA-MPJPE, MHR-70 (mm) ↓	—	27.3 (10.1)	23.7 (7.1)

Multi-view consistency rows: means; *teacher agreement* rows: medians (σ_{NIQR}). Sapiens is the *teacher*, so it bounds the 2D rows.

- Prior benchmark: reprojection 39.8 → 36.7 px, GC@10 0.31 → 0.36.

QUALITATIVE



Three held-out infants; labelled joint = largest gain toward the Sapiens target (black star). **Shape artifacts persist** — adult-proportioned face, over-narrow torso, absent from the pseudo-labels.

- **Open:** the mesh *shape* stays adult-proportioned — MHR’s shape space is adult-mean — and the dense render terms contribute only 2% of the converged objective.
- **Next:** an infant-capable shape model (ANNY), and the biomechanical head below, so infant movement is returned as clinically interpretable joint angles.